The Magnetic Properties of Superparamagnetic Particles by a Monte Carlo Method

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We develop and carry out Monte Carlo simulations for an ensemble of superparamagnetic particles uniformly distributed in a nonmagnetic matrix. We find the magnetization below the blocking temperature \( T_B \) when it shows hysteresis and above \( T_B \) in the superparamagnetic region. We determine the blocking temperature for a set of anisotropy strengths from the magnetization and the susceptibility of the particles. A fixed number of Monte Carlo steps with a constrained acceptance rate is shown to be equivalent to an observation time in the simulations that is much shorter than experimental observation times. We show how the blocking temperature obtained in the simulations can be converted into the corresponding experimentally measurable blocking temperature by using this difference in the observation times. This provides a new method to compare Monte Carlo simulation results with experiments, such as recent ones on fcc Co particles.

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A number of numerical simulations have been performed to study the magnetic properties of clusters or very small particles both at nonzero\(^{1–8}\) and at zero temperatures.\(^9,10\) The nonzero temperature properties have been studied in Monte Carlo (MC) simulations\(^1,2\) assuming that the anisotropy of the particles can be neglected. While this assumption is reasonable when the particles are studied on an atomic level or when the magnetization of the particles behaves essentially paramagnetically, it excludes the low temperature properties when the magnetization shows hysteresis due to the anisotropy. Here we intend to study the combination of temperature and anisotropy effects on the magnetization of fine magnetic particles using the Metropolis Monte Carlo scheme.\(^11\)

The description of the magnetic properties of single-domain particles in general for nonzero temperatures is based on the superparamagnetic theory.\(^12\) The basic assumption of this theory is that the atomic magnetic moments within a particle are moving coherently and thus its magnetic moment can be represented by a single vector with a magnitude equal to \( \mu = \mu_0 N \), where \( \mu_0 \) is the atomic magnetic moment in Bohr magnetons and \( N \) is the number of atoms in the particle. The magnetic moment of the particle is considered coupled to a uniaxial anisotropy, for instance due to crystal or stress anisotropy, and to the external magnetic field. In the absence of an external field, the uniaxial anisotropy leads to two equivalent equilibrium states of the moment. For an ensemble of identical particles which have been initially saturated in a given direction, the magnetization per particle will decrease from its initial value as \( M = M_s e^{-t/\tau} \), where \( M_s = \mu/V \) and \( V \) is the particle’s volume, as equal populations of the two states are acquired due to thermal fluctuations. The relaxation time \( \tau \) is essentially the average time to reverse a particle’s magnetization from one of the equilibrium states to the other, and is determined by the Boltzmann factor \( \exp (-D/k_B T) \) and a characteristic constant frequency \( f_0 \) (of the order of \( 10^{10} \) Hz) through the relation

\[
\frac{1}{\tau} = f_0 \exp(-D/k_B T),
\]

where \( T \) is the temperature, \( k_B \) is Boltzmann’s constant and \( D \) is the energy barrier separating the two states.\(^13\) \( D \) is determined by the anisotropy energy density \( K \) and the particle’s volume, \( D = KV \). For high \( T \) \( (k_B T \gg D) \) the time-scale of the thermal relaxation \( \tau \) in Eq. (1) is much shorter than any experimental observation time over which magnetization is measured, so the system appears superparamagnetic. On the other hand, for low \( T \) \( (k_B T \ll D) \), the thermal reversal time scale \( \tau \) becomes very large, much larger than any observation time, and the system appears ferromagnetic. The temperature determined from Eq. (1) with \( \tau \) set equal to the experimental observation time \( t \) defines the blocking temperature \( T_B \) which separates the two regimes. However, the time \( t \) is determined by the experimental requirements, so the definition of \( T_B \) is not unique, but can depend on the type of experiment. For \( t = 1000 \) \( (sec) \) we have

\[
T_B \approx D/30k_B,
\]

where the numerical factor comes from \( \ln(f_0t) \approx 30 \) for \( f_0 = 10^{10} \) Hz. If we want to use Monte Carlo or even a spin dynamics simulation based on Landau—Lifshitz or Langevin equations to study the magnetic properties in the presence of anisotropy, it is impossible to make a long enough simulation that will correspond to 1000 seconds.
Therefore, part of our goal here is to describe how a laboratory value of \( T_B \) can be obtained from simulations that correspond to observation times much less than 1 second. We show in this paper that all of the results in the superparamagnetic theory can be obtained by Monte Carlo simulations where we use an observation time much smaller than the experimentally used values. Nevertheless, the data from the simulations can be compared with experimental results after we account for the shorter observation time of the Monte Carlo simulations.

We choose to do the simulations by using a Metropolis Monte Carlo scheme rather than using Landau—Lifshitz or Langevin equations because the implementation of the temperature is straightforward. However, it presents the usual problem with MC schemes that individual MC steps do not correspond to real time, but are only sampling the phase space at some rate. If the MC acceptance rate can be set to some desired value (we use 30 to 40%), however, this effectively sets the rate of motion in phase space. For the problem here, the magnetic moment can remain for many steps in one side of the double potential well due to the anisotropy term. Over some characteristic number of MC steps, it will typically pass near the barrier to go to the other side of the well. That is, there really will be a characteristic attempt frequency to jump to the other well, measured in attempts per MC step. This frequency should correspond approximately to \( f_0 \) in Eq. (1), and implies the conversion of MC steps, or “MC time”, into real time. We do not, however, try to measure the characteristic frequency directly in MC simulations. Instead, we use a fixed large number (1.2 \( \times 10^6 \)) of MC steps, keeping the acceptance rate from 30% to 40%, and determine \( T_B \) from magnetization and susceptibility results for different values of \( D \). We find a linear relation between \( T_B \) and \( D \), as in Eq. (2), but with the numerical factor of approximately 14.8 instead of 30. The smaller numerical factor is interpreted to mean that the 1.2 \( \times 10^6 \) MC steps correspond to a much shorter “observation time” \( t_{MC} \) than the 1000 (s) applied in Eq. (2), according to \( \ln(f_0 t_{MC}) \approx 14.8 \).

By understanding this effective physical time scale over which the MC averages were made, it allows us to infer the corresponding laboratory measurements that would be made at the 1000 (s) time scale. Although the model used here is simple, these ideas are important for the interpretation of any simulation of a more realistic model of fine magnetic particles with metastable states relaxing over a barrier at finite \( T \).

We assume that our system consists of an assembly of spherical particles with identical sizes. The particles are embedded in a nonmagnetic matrix and can be considered approximately as noninteracting. Due to the spherical shape of the particles we assume that the origin of the anisotropy is only from crystal anisotropy. Such a kind of a system has been realized experimentally (see, for example, Ref. 14).

Next, we assume that the magnetization is homogeneously distributed throughout the volume of the particle and thus can be represented by a single vector with a constant magnitude. The Hamiltonian of each particle is

\[
\mathcal{H} = -\mu \vec{H} \cdot \vec{S} - D(\vec{n} \cdot \vec{S})^2, \quad (3)
\]

where \( \vec{H} \) is the external magnetic field, \( \vec{S} \), the “spin” of the particle, is a unit vector along its magnetization, and \( \vec{n} \) is a unit vector along the particle’s anisotropy axis. The \( \vec{n} \)—vectors of the particles are assumed to be uniformly distributed in all directions. When we calculate the component of the magnetization of the system along the field, it is enough to calculate the average magnetization of the particles with anisotropy axes \( \vec{n} \) in a single plane which includes the direction of the field \( \vec{H} \). The magnetization of the system will then be obtained using the azimuthal symmetry about the direction of the field. We chose the \( z \)-axis to be along \( \vec{H} \) and take the \( xz \)-plane as the plane containing \( \vec{H} \) and \( \vec{n} \). The Hamiltonian of each particle is invariant under the transformation \( \vec{n} \to -\vec{n} \) so we may restrict the angle \( \theta \) between the field \( \vec{H} \) and a given anisotropy axis \( \vec{n} \) in the interval \( 0 \leq \theta \leq \pi/2 \). To obtain the magnetization per particle and the susceptibility of the system we perform two averages. First, we determine the thermal averages \( \langle S_z \rangle_\theta \) and \( \langle S_z^2 \rangle_\theta \) for a given \( \vec{n}(\theta) \) by Monte Carlo simulations, and second, we average these results over the uniform distribution of \( \vec{n} \) on the unit sphere. Then the magnetization per particle will be

\[
M = M_s \langle S_z \rangle = M_s \int_0^{\pi/2} \langle S_z \rangle_\theta \sin \theta d\theta \quad (4)
\]

and the mass susceptibility is

\[
\chi = \frac{\mu_0 
}{k_B T} \int_0^{\pi/2} (\langle S_z^2 \rangle_\theta - \langle S_z \rangle_\theta^2) \sin \theta d\theta, \quad (5)
\]

with thermal averages

\[
\langle S_z^k \rangle_\theta = \int e^{-\beta \mathcal{H}(\theta, \theta')} S_z^k d\Omega' / \int e^{-\beta \mathcal{H}(\theta, \theta')} d\Omega' \quad (6)
\]

for \( k = 1, 2 \) and \( \mathcal{H}(\theta, \theta') = -\mu H S_z - D(n_x S_x + n_z S_z)^2, \) \( \vec{S} = (\sin \theta' \cos \phi', \sin \theta' \sin \phi', \cos \theta'), \) \( \vec{n} = (\sin \theta, 0, \cos \theta), \) \( \beta = 1/k_B T, \) \( d\Omega' = \sin \theta' d\phi' d\theta' \). The saturation magnetization \( \sigma_s = M_s V/m \) is in (emu/g), \( m \) is the particle’s mass, and the magnetic moment \( \mu \) of the particle is in Bohr magnetons.

The average over the distribution of anisotropy axes, i.e., taking the integrals in Eq. (4) and Eq. (5), is performed numerically using the extended midpoint rule, dividing the interval \( 0 < \theta \leq \pi/2 \) into 90 parts and incrementing \( \theta \) by \( \Delta \theta = 1 \) degree. The thermal averages \( \langle S_z \rangle_\theta \) and \( \langle S_z^2 \rangle_\theta \), defined by Eq. (6), are calculated in the Monte Carlo simulations for each \( \theta \) using the Metropolis algorithm.11 The most important part of our implementation of the Monte Carlo simulation is in the way of performing Monte Carlo steps (MCS). In a Monte Carlo step an attempt to change the spin from \( \vec{S}_{old} \) to \( \vec{S}_{new} \) is
made such that the deviation of $\hat{S}_{\text{new}}$ from $S_{\text{old}}$ is small but randomly chosen with a fixed limit $\delta S_{\text{max}}$. This approach allows the freedom to control the acceptance rate of MC moves by adjusting the limit $\delta S_{\text{max}}$ and, more importantly, models the real system more accurately than other schemes used$^2$ where $S_{\text{new}}$ is completely randomly chosen independently from $S_{\text{old}}$. It is very important to understand that if we employed this latter type of move the system would always be paramagnetic for any $T > 0$ and no hysteresis would result. That is, for completely random and independent moves arbitrarily large fluctuations are allowed in a single Monte Carlo step and the system will escape very quickly from any metastable state which may be responsible for hysteresis. We actually perform the Monte Carlo in such a way that it samples the phase space only “locally” (near current position), allowing for confinement into metastable states responsible for the phase space sampling rate, it is then possible to observe the same for different temperatures. By using a constant rate of sampling. In this way, the mapping of MC “time” to experimental time will be considered to be the same for different temperatures. By using a constant phase space sampling rate, it is then possible to observe the obvious change from fast relaxation in the superparamagnetic regime, to slower relaxation in the ferromagnetic regime.

The next $1.2 \times 10^6$ MCS are used to collect data but the consecutive measurements are taken with a specific interval of MCS between them to minimize the correlation in the data. In the sense of our above discussion, the observation time of the simulation is determined by the number of MCS $N_{\text{MC}} = 1.2 \times 10^6$ made, with a fixed acceptance rate, for each measurement. When changing either $H$ or $T$ a new fine equilibration is performed, adjusting also the acceptance rate before collecting data again. To consider how to use our simulation data to find $T_B$, we review how $T_B$ is found in real experiments.

In experiments, the blocking temperature is determined by scanning $M(T)$ or $\chi(T)$, starting from a zero field cooled sample and then applying a very small field and taking measurements as a function of $T$. The magnetization of the system is very close to zero for very low temperature since approximately half of the particles with a particular anisotropy axis $\hat{n}$ have their moments along $\hat{n}$ and the other half along $-\hat{n}$; $\hat{n}$ is also uniformly distributed on the unit sphere. That is, the thermal fluctuations are very weak ($k_B T \ll D$), and they cannot move the moments from the metastable state (moment has component against $H$) to the global equilibrium state (moment has component along $H$) implied by the presence of the very small field, $\mu H \ll D$. Equivalently, the relaxation time $\tau$ in Eq. (1) will be much greater than any physical observation time. Increasing $T$ will increase the thermal fluctuations ($\tau$ decreases) and thus the probability for a transition from the metastable state to the equilibrium state. This will increase $(S_z)$. The increase will continue until the system reaches $T_B$. The assembly of particles will be in the superparamagnetic region for $T > T_B$ and $(S_z)$ will decrease accordingly when we further continue to increase $T$. $T_B$ can also be determined from the inverse susceptibility, which will have a minimum for $T = T_B$ and will increase linearly with $T$ in the superparamagnetic region.

To determine $T_B$ in the simulations we follow the experimental procedure. We start with two spins for each $\theta$. Initially one of them is along $\hat{n}$ and the other along $-\hat{n}$ since in the zero field cooled sample one half of the particles with this $\hat{n}$ will have on the average their magnetization along $\hat{n}$ and the other half along $-\hat{n}$. Then we apply very small constant field $H$ and start to calculate $M(T)$. This is done for a number of values of the anisotropy coupling constant $100 \leq D/k_B \leq 700$ (K). These are typical values, for instance, for Co particles where $K_{\text{bulk}} = 2.7 \times 10^6$ (erg/cm$^3$). Different values of $D$ will correspond to different sizes of particles. The reduced magnetization $M/M_s$ ($M_s$ is the saturation magnetization) obtained by simulation (zero field cooled) is shown in Fig. 1 as function of $T$ for $H = 500$ (Oe) and different values of $D/k_B$. Selected error bars are shown in the superparamagnetic region; the error bars for $T < T_B$ are of the size of the symbols used or smaller. Changing the value of $H$ to 100 (Oe) did not change the observed position of the peak of the magnetization but made the data more noisy, particularly for large $D$ when $\mu H$ is more than two orders of magnitude smaller than $D$. The susceptibility is shown in Fig. 2 for the same set of

![FIG. 1. Dependence of the reduced magnetization on the temperature for zero cooled system and different values of $D/k_B$. The external field is constant and equal to 500 (Oe).](image-url)
parameters. The blocking temperatures determined from the peak of the magnetization or from the minimum of the susceptibility do not differ by more than 1 (K). The dependence of $T_B$ on $D$ and a linear fit are shown in Fig. 3. We have $D/k_B T_B^{MC} = 14.81 \pm 0.25$ from the slope of the linear fit. Therefore, if we assume that the characteristic frequency $f_0$ is the same as in the experiment ($10^{10}$ Hz) we can use Eq. (1) to define an effective observation time $t_{MC}$ of the Monte Carlo simulations. Substituting $D/k_B T_B^{MC} = 14.81$ in Eq. (1), we obtain $t_{MC} = 2.70 \times 10^{-4} (s)$ for a measurement consisting of $N_{MC} = 1.2 \times 10^6$ MCS. Increasing the number of MCS decreases $T_B^{MC}$ and increases $t_{MC}$ but to use a relaxation time equal to 1000 (s) in the simulations we would have to use approximately $1.2 \times 10^6 \times \exp(15.21)$ MCS per data point.

Nevertheless, we can compare the magnetization curves from our simulations with the experimental ones after we take into account the much smaller observation time in the simulations compared to the observation time of 1000 (s) used in the experiments. To account for this difference we have to consider the measurement of the magnetization in two intervals of time with different lengths. If the temperature and the magnetic field are fixed, the magnetization measured in intervals of time $t_1$ and $t_2$ ($t_1 < t_2$) will be greater for the shorter interval of time $t_1$ since the magnetization will fluctuate less on a shorter time scale. Thus, if we are to measure the same value of the magnetization in two intervals of time $t_1 \neq t_2$ at the same external field, we have to perform the measurements at different temperatures. A particular rate of the fluctuations in a given interval of time can be seen in a shorter interval of time if the temperature is higher since the rate of fluctuations of the magnetization will increase with temperature. Therefore, we expect that a value of the magnetization measured in an interval of time $t_1$ and at temperature $T_1$ should be measured also in a time interval $t_2$ ($t_1 \neq t_2$) but at temperature $T_2$ such that $T_1/T_{B1} = T_2/T_{B2}$, where $T_{B1}$ and $T_{B2}$ are the blocking temperatures determined from Eq. (1) with relaxation time $\tau$ set to $t_1$ and $t_2$ respectively.

We can also apply Eq. (1) to obtain a relation between the blocking temperature in MC simulations and the blocking temperature in experiments. If an MC observation time $t_{MC}$ leads to a blocking temperature $T_B^{MC}$, and the longer laboratory observation time $t_L$ leads to the lower blocking temperature $T_B^L$, then these are related by

$$
\frac{D}{k_B T_B^L} = \frac{D}{k_B T_B^{MC}} + \ln \left( \frac{t_L}{t_{MC}} \right).
$$

If the absolute scale of time for the MC simulation were known, then this would specify how to obtain the laboratory blocking temperature from the simulation. However, $t_{MC}$ is not known in an absolute sense, since the “time” in the MC simulation is measured only in MC steps, with no physical dimensions. Alternatively, we can adopt a different interpretation of Eq. (7). In the MC simulation we found $D/k_B T_B^{MC} = 14.81$, and we can use Eq. (7) to determine the value of $t_{MC}$ that recovers the usual experimental result, $D/k_B T_B^L \approx 30$. Using $t_L = 10^3 (s)$, this leads to $t_{MC} = t_L \exp (-15.12) = 2.70 \times 10^{-4} (s)$, the same value as stated earlier. We should also note that Eq. (7) can be generalized to the case where the anisotropy constant $D$ takes a different value in the simulation than in the laboratory, (i.e., change $D \to D'$ on RHS.) The formula really only specifies how the ratio $D/T_B$ changes with observation time.

With these ideas in mind, we can compare our results from the simulations with the data for fcc Co particles 18 (Å) in diameter. The experimental values for the anisotropy energy and the magnetic moment per particle are $D/k_B \approx 648$ (K) and $\mu = 550 \mu_B$ with $T_B = 22 \pm 2$ (K). The blocking temperature determined from the
Monte Carlo simulations (Fig. 1) for $D/k_B = 648 (K)$ is

$T_B^{MC} = 44 \pm 1 (K)$. By Eq. (7), this maps into $T_B = 21.7$

(K), in agreement with the experimental value, as must be the case, because the experimental value of anisotropy constant is determined from the experimental blocking temperature via Eq. (2).

The hysteresis loops (magnetization for $H$ increasing only) are shown in Fig. 4 for the same value of $D/k_B$ and a set of temperatures $T < T_B$. The observed coercivity agrees well with the theoretical value given by

$$H_c = 0.48 \times \frac{2K}{M_s} (1 - \sqrt{T/T_B}).$$

for an assembly of particles with randomly oriented anisotropy axes. The inset of Fig. 4 shows $h_c = H_c/H_{0\alpha}$, where $H_{0\alpha} = 0.96K/M_s$, from the Monte Carlo data and from the theory. The reduced remanent magnetization $M_r/M_s$ also agrees well with the theoretical value of 0.5 and starts to deviate from it when $T$ approaches $T_B$.

While the values of $h_c$ are in good agreement with the superparamagnetic theory, the experimental values for the same ratio of $T/T_B$ are approximately one order of magnitude smaller. This could be caused by existence of imperfections in the crystal structure of the particles though it does not seem to be the case. There are also considerable deviations from the bulk properties when the size of the particles is decreased. For instance, the 18 Å in diameter particles show anisotropy energy density about an order of magnitude larger than the bulk value and the atomic magnetic moment also increases. These are attributed to surface effects which should lead to deviations from coherent rotation of the atomic magnetic moments, particularly of the surface spins which have less nearest neighbors and could fluctuate more. The number of surface sites is considerable in such small particles so the smaller coercivity may be due to surface effects too.

Finally, the magnetization curves for three values of the temperature above $T_B$ are shown in Fig. 5 again for $D/k_B = 648 (K)$. These results show that the MC simulations are consistent with the superparamagnetic behavior which is illustrated by the overlap of the magnetization curves when plotted vs. $H/T$, the inset in this figure. The experiment also shows superparamagnetic behavior but with approximately half as large saturation magnetization at large external magnetic fields for the same values of $T/T_B$ which is attributed to a core—shell structure of the particles with a saturation magnetization of the shell of the particle much smaller than the net magnetic moment of the atoms in the shell. Since the small saturation magnetization of the particles at large fields cannot be obtained assuming coherent rotation of the atomic spins, it is of importance to consider the magnetic properties of the particles with their internal structure taken into account when the surface starts to dominate their properties.

In conclusion, we carried out Monte Carlo simulations for an assembly of particles with randomly oriented uniaxial anisotropy. The simulation recovers all of the results in the superparamagnetic theory. The observation time in the Monte Carlo simulations is much smaller than the corresponding time in the experiments. The effect of the smaller observation time leads to a higher blocking temperature in the simulations and generally the superparamagnetic properties which are observed in the experiments for a given temperature should be observed in the simulations at a higher temperature. A compar-

FIG. 4. One half of the hysteresis loops for a set of temperatures below $T_B$, where $T_B = 44 (K)$. The inset shows the comparison of the reduced coercivity $h_c$ (see the text) with the superparamagnetic theory.

FIG. 5. Reduced magnetization of the system vs. $H$ for $T > T_B = 44 (K)$. The inset shows the overlap of the magnetization curves when plotted vs. $H/T$. The error bars are of the order of the symbols or smaller.
ison of the simulations with the experiments on fcc Co particles 18 Å in diameter for the same ratio of $T/T_B$ shows that while the properties of these particles are generally superparamagnetic there are two deviations from the theory and from the simulations. The coercivity in the experiment is about an order of magnitude smaller than the values of the coercivity in the superparamagnetic theory and in the simulations, and the saturation magnetization for $T > T_B$ is about half as large as in our simulations. These deviations are assumed to be caused by the surface of these particles which requires a study of such particles on an atomic level. The method we have used suggests a possible extension for simulations on a single particle with its atomic structure considered and anisotropy included.

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13 In the presence of a weak external field, there can be two energetically inequivalent equilibrium magnetization states, and Eq. (1) will be modified to include the field interaction. The higher energy (metastable) state, with a component of $M$ against $H$, will have a smaller relaxation time $\tau$ than the lower energy state, with a component of $M$ along $H$.