

## Prefixes

a=10<sup>-18</sup>, f=10<sup>-15</sup>, p=10<sup>-12</sup>, n=10<sup>-9</sup>, μ = 10<sup>-6</sup>, m=10<sup>-3</sup>, c=10<sup>-2</sup>, k=10<sup>3</sup>, M=10<sup>6</sup>, G=10<sup>9</sup>, T=10<sup>12</sup>, P=10<sup>15</sup>

## Physical Constants

$g = 9.80 \text{ m/s}^2$  (gravitational acceleration)  
 $M_E = 5.98 \times 10^{24} \text{ kg}$  (mass of Earth)  
 $m_e = 9.11 \times 10^{-31} \text{ kg}$  (electron mass)  
 $c = 299792458 \text{ m/s}$  (exact speed of light)

$G = 6.67 \times 10^{-11} \text{ N}\cdot\text{m}^2/\text{kg}^2$  (Gravitational constant)  
 $R_E = 6380 \text{ km}$  (mean radius of Earth)  
 $m_p = 1.67 \times 10^{-27} \text{ kg}$  (proton mass)

## Units and Conversions

1 inch = 1 in = 2.54 cm (exact)

1 foot = 1 ft = 12 in = 30.48 cm (exact)

1 mile = 5280 ft (exact)

1 mile = 1609.344 m = 1.609344 km (exact)

1 m/s = 3.6 km/hour (exact)

1 ft/s = 0.6818 mile/hour

1 acre = 43560 ft<sup>2</sup> = (1 mile)<sup>2</sup>/640 (exact)

1 hectare = 10<sup>4</sup> m<sup>2</sup> (exact)

## Trig summary

$\sin \theta = (\text{opp})/(\text{hyp})$ ,       $\cos \theta = (\text{adj})/(\text{hyp})$ ,       $\tan \theta = (\text{opp})/(\text{adj})$ ,       $(\text{opp})^2 + (\text{adj})^2 = (\text{hyp})^2$ .  
 $\sin \theta = \sin(180^\circ - \theta)$ ,       $\cos \theta = \cos(-\theta)$ ,       $\tan \theta = \tan(180^\circ + \theta)$ ,       $\sin^2 \theta + \cos^2 \theta = 1$ .

## OpenStax Ch. 1 Equations

Percent uncertainty:

If a measurement = value ± uncertainty,      percent uncertainty = (uncertainty/value) × 100 %.

## OpenStax Ch. 2 Equations

Motion:

$\bar{v} = \Delta x / \Delta t$ ,     $\Delta x = x - x_0$ ,    slope of  $x(t)$  curve =  $v(t)$ .      Quadratic eqn.:  $ax^2 + bx + c = 0$ .  
 $\bar{a} = \Delta v / \Delta t$ ,     $\Delta v = v - v_0$ ,    slope of  $v(t)$  curve =  $a(t)$ .      Solution:  $x = [-b \pm \sqrt{b^2 - 4ac}] / (2a)$ .

For constant acceleration in one-dimension:

$\bar{v} = \frac{1}{2}(v_0 + v)$ ,     $v = v_0 + at$ ,     $x = x_0 + v_0t + \frac{1}{2}at^2$ ,     $v^2 = v_0^2 + 2a(x - x_0)$ .

For free fall on Earth, using an upward  $y$ -axis, with  $g = 9.80 \text{ m/s}^2$  downward:

$\bar{v}_y = \frac{1}{2}(v_{0y} + v_y)$ ,     $v_y = v_{0y} - gt$ ,     $y = y_0 + v_{0y}t - \frac{1}{2}gt^2$ ,     $v_y^2 = v_{0y}^2 - 2g\Delta y$ .

## OpenStax Ch. 3 Equations

Vectors

Written  $\vec{V}$  or  $\mathbf{V}$ , described by magnitude= $V$ , direction= $\theta$  or by components ( $V_x$ ,  $V_y$ ).

$V_x = V \cos \theta$ ,     $V_y = V \sin \theta$ ,

$V = \sqrt{V_x^2 + V_y^2}$ ,     $\tan \theta = V_y / V_x$ .       $\theta$  is the angle from  $\vec{V}$  to  $x$ -axis.

Addition:  $\mathbf{A} + \mathbf{B}$ , head to tail.      Subtraction:  $\mathbf{A} - \mathbf{B}$  is  $\mathbf{A} + (-\mathbf{B})$ ,     $-\mathbf{B}$  is  $\mathbf{B}$  reversed.

Projectiles

$a_x = 0$ ,     $v_x = v_{0x}$ ,     $x = x_0 + v_{0x}t$ .      For a horizontal  $x$ -axis.

$a_y = -g$ ,     $v_y = v_{0y} - gt$ ,     $y = y_0 + v_{0y}t - \frac{1}{2}gt^2$ .      For an upward  $y$ -axis.

$R = (v_0^2/g) \sin 2\theta_0$ ,    (Range for level ground only.)

Relative Motion

$\vec{V}_{BS} = \vec{V}_{BW} + \vec{V}_{WS}$ ,      B=Boat, S=Shore, W=Water.      BS means "boat relative to shore", etc.

## OpenStax Ch. 4 Equations

Newton's First Law:

$$\vec{a} = 0 \text{ unless } \vec{F}_{\text{net}} \neq 0.$$

Newton's Second Law:

$$\vec{F}_{\text{net}} = m\vec{a}, \quad \text{means } \Sigma F_x = ma_x \text{ and } \Sigma F_y = ma_y. \quad \vec{F}_{\text{net}} = \Sigma \vec{F}_i, \text{ sum over all forces on a mass.}$$

Newton's Third Law:

$$\vec{F}_{\text{A on B}} = -\vec{F}_{\text{B on A}}.$$

Gravitational force (weight) near Earth:

$$F_g = mg, \text{ downward.}$$

Gravitational force components on inclines:

$$F_{g\parallel} = mg \sin \theta, \quad F_{g\perp} = mg \cos \theta, \quad \text{for incline at angle } \theta \text{ to horizontal.}$$

## OpenStax Ch. 5 Equations

Normal force  $N$

$N$  is the force acting perpendicular to a surface, on the object acted on by friction.

Friction magnitude (opposes the relative motion of two surfaces) depends on  $N$ :

$$f_s \leq \mu_s N \quad (\text{static friction}). \quad f_k = \mu_k N \quad (\text{kinetic or sliding friction}).$$

## Chapter 6 Equations

Centripetal Acceleration:

$$a_c = v^2/r = \omega^2 r, \text{ towards the center of the circle. Use } \omega \text{ in rad/sec!}$$

Circular motion:

speed  $v = 2\pi r/T = 2\pi r f$ , frequency  $f = 1/T$ , where  $T$  is the period of one revolution.

speed  $v = \omega r$ , angular speed  $\omega = 2\pi f = 2\pi/T$ ,  $\omega$  is in rad/sec.

Gravitation:

$$F = Gm_1m_2/r^2; \quad g = GM/r^2, \quad \text{where } G = 6.67 \times 10^{-11} \text{ Nm}^2/\text{kg}^2;$$

Orbits:

$$v^2/r = g = GM/r^2; \quad v = \sqrt{GM/r}. \quad \text{centripetal acceleration} = \text{free fall acceleration.}$$

## Chapter 7 Equations

Work & Kinetic & Potential Energies:  $F_{\text{gravity},y} = -mg$ ,  $F_{\text{spring}} = -kx$ .

$$W = Fd \cos \theta, \quad \text{KE} = \frac{1}{2}mv^2, \quad \text{PE}_{\text{gravity}} = mgy, \quad \text{PE}_{\text{spring}} = \frac{1}{2}kx^2. \quad \theta = \text{angle btwn } \vec{F} \text{ and } \vec{d}.$$

Conservation or Transformation of Energy:

**Work-KE theorem:**

$$\Delta \text{KE} = W_{\text{net}} = \text{work of all forces.}$$

**General energy-transformation law:**

$$\Delta \text{KE} + \Delta \text{PE} = W_{\text{NC}} = \text{work of non-conservative forces.}$$

Power:

$$P_{\text{ave}} = W/t, \quad \text{or use } P_{\text{ave}} = \text{energy/time.}$$