

Chapter 6 Equations

Work & Kinetic & Potential Energies:

$$W = Fd \cos \theta, \quad \text{KE} = \frac{1}{2}mv^2, \quad \text{PE}_{\text{gravity}} = mgy, \quad \text{PE}_{\text{spring}} = \frac{1}{2}kx^2.$$

Conservation or Transformation of Energy:

“work-KE theorem” $\Delta\text{KE} = W_{\text{net}}$, **or use conservation law** $\Delta\text{KE} + \Delta\text{PE} = W_{\text{NC}}$.

Power:

$$P_{\text{ave}} = \frac{W}{t}, \quad \text{or use } P_{\text{ave}} = \frac{\text{energy}}{\text{time}}.$$

Chapter 5 Equations

Centripetal Acceleration:

$$a_R = \frac{v^2}{r}, \text{ towards the center of the circle.}$$

Circular motion:

$$\text{speed } v = \frac{2\pi r}{T} = 2\pi r f, \text{ frequency } f = \frac{1}{T}, \text{ where } T \text{ is the period of one revolution.}$$

Gravitation:

$$F = G \frac{m_1 m_2}{r^2}; \quad g = \frac{GM}{r^2}, \quad \text{where } G = 6.67 \times 10^{-11} \text{ Nm}^2/\text{kg}^2;$$

Orbits:

$$\frac{v^2}{r} = g = \frac{GM}{r^2}; \quad v = \sqrt{\frac{GM}{r}}.$$

Chapter 4 Equations

Newton's Second Law:

$$\vec{F}_{\text{net}} = m\vec{a}, \text{ which means } \Sigma F_x = ma_x \text{ and } \Sigma F_y = ma_y.$$

Static friction (magnitude):

$$f_s \leq \mu_s N \text{ or } F_{\text{fr}} \leq \mu_s F_N.$$

Kinetic or sliding friction (magnitude):

$$f_k = \mu_k N \text{ or } F_{\text{fr}} = \mu_k F_N.$$

Gravitational force near Earth:

$$F_G = mg, \text{ downward.}$$

Acceleration Equations

$$\bar{v} = \frac{\Delta x}{\Delta t}, \quad \Delta x = x - x_0, \quad \text{slope of } x(t) = v(t).$$

$$\bar{a} = \frac{\Delta v}{\Delta t}, \quad \Delta v = v - v_0, \quad \text{slope of } v(t) = a(t).$$

For constant acceleration in one-dimension:

$$\bar{v} = \frac{1}{2}(v_0 + v), \quad v = v_0 + at, \quad x = x_0 + v_0 t + \frac{1}{2}at^2, \quad v^2 = v_0^2 + 2a(x - x_0).$$

Vectors

Written \vec{V} or \mathbf{V} , described by magnitude= V , direction= θ or by components (V_x, V_y) .

$$V_x = V \cos \theta, \quad V_y = V \sin \theta,$$

$$V = \sqrt{V_x^2 + V_y^2}, \quad \tan \theta = \frac{V_y}{V_x}. \quad \theta \text{ is the angle from } \vec{V} \text{ to } +x\text{-axis.}$$

Addition: $\mathbf{A} + \mathbf{B}$, head to tail. Subtraction: $\mathbf{A} - \mathbf{B}$ is $\mathbf{A} + (-\mathbf{B})$, $-\mathbf{B}$ is \mathbf{B} reversed.

Trig summary

$$\sin \theta = \frac{(\text{opp})}{(\text{hyp})}, \quad \cos \theta = \frac{(\text{adj})}{(\text{hyp})}, \quad \tan \theta = \frac{(\text{opp})}{(\text{adj})}, \quad (\text{opp})^2 + (\text{adj})^2 = (\text{hyp})^2.$$

$$\sin \theta = \sin(180^\circ - \theta), \quad \cos \theta = \cos(-\theta), \quad \tan \theta = \tan(180^\circ + \theta), \quad \sin^2 \theta + \cos^2 \theta = 1.$$